

Civil status Married, 3 children

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Languages

Danish - native English - professional German - elementary

Mikkel Fly Kragh

MSc, PhD

Experience

May. 24 - Now Freelance: Al Tech Lead

Trifork A/S

At Trifork, I'm involved in two projects:

- Development and deployment of real-time computer vision systems for advanced driver assistance systems (ADAS)
- Development and validation of clinical prediction models for the Danish healtcare system

Feb. 23 - Now Computer Vision and Machine Learning specialist

Co-founder, Al Lab ApS

Co-founder of Al Lab ApS (theailab.dk), an Al consultancy and development house located in Aarhus, Denmark. We offer prototype development, consultancy services and vision systems within the area of computer vision and deep learning.

Apr. 22 - Now **External examiner**

Danish Agency for Higher Education and Science

External examiner (censor in Danish) on BSc and MSc engineering and master programs in Denmark. As an external examiner, I have assessed and graded both BSc and MSc theses within the areas of machine learning, deep learning, computer vision, and robotics.

Sep. 22 - Apr. 24 Freelance: Computer Vision Engineer

CARIAD, Volkswagen Group

Active learning (intelligent data collection) algorithms for self-driving cars. Deep learning model training for semantic segmentation and object detection. Model quantization with ONNX and ONNX Runtime (CPU/Cuda/TensorRT). Large investigation and usage of multiple experiment tracking tools. Modern Python development of a machine learning system (MLOps, experiment tracking, CI/CD in Azure, code review, pre-commits, linting, type-hints and environments).

Aug. 21 - Aug. 22 Senior Research Scientist

Vitrolife A/S

Use of deep learning and computer vision to optimize assisted reproduction technologies. As a research scientist, I was in charge of prototyping emerging technologies within machine learning, such as:

- Self-supervised learning on ~500,000 videos of fertilized human eggs
- Bias identification and mitigation using adversarial domain adaptation
- Uncertainty estimation and separation using ensemble models
- · Model calibration using multivariate logistic regression
- Clinical relevance investigation of evaluation metrics for discrimination, calibration, and ranking performance of prediction models.

Additionally, I was in charge of scientific communication and research collaboration with both fertility clinics and universities. Here, I supervised BSc, MSc and PhD students in their scientific and AI-related collaborations with Vitrolife.

May. 18 - Jul. 21 Industrial Postdoc

Vitrolife A/S

Automatic Scoring and Selection of Embryos for Improving Standard IVF Treatment (ASSIST).

Developed deep learning models on microscopy imaging surpassing human-level performance on embryo quality assessment. These models (Guided AnnotationTM and iDAScore®) are currently in production and used daily by hundreds of fertility clinics worldwide.

Dec. 14 - Apr. 18 PhD Student

Department of Engineering, Aarhus University

Lidar Sensing for Object Detection and Classification in Agriculture.

The project was part of the Safer Autonomous Farming Equipment (SAFE) project (Innovation Fund Denmark). I worked with sensor fusion techniques combining lidar sensing with color and thermal imaging as well as radar.

Education

Dec. 14 - Apr. 18 PhD

Department of Engineering, Aarhus University

Thesis: "Lidar Sensing for Object Detection and Classification in Agriculture"

Jan. 12- Jan. 14 Master of Science in Information Technology

Department of Engineering, Aarhus University

MSc thesis: "Inspection of Glass Containers using Multi-target Particle Track-

ing and 3D Positioning"

ECTS weighted average: 11.9 (7-step-scale)

Aug. 08 - Jan. 12 Bachelor of Engineering in Electronics and Computer Engineering

Aarhus School of Engineering

BSc thesis: "InSpot Intelligent Spotlight" ECTS weighted average: 11.6 (7-step-scale)

Selected Courses

Aug. 15 Summer School in Field Robotics

University of Southern Denmark PhD course, 7.5 ECTS

Apr. 15 - Jul. 15 Deep Learning for Image Analysis

Department of Engineering, Aarhus University

PhD reading course, 5 ECTS

Feb. 13 - Apr. 13 Artificial Intelligence for Robotics

Udacity (online)

MSc reading course, 5 ECTS

Mar. 12 - Jun. 13 Computer Vision

Department of Engineering, Aarhus University

MSc course, 5 ECTS

Dec. 16 - Jan. 18 Self-Driving Car Engineer Nanodegree Program

Udacity (online)

PhD course collection, 10 ECTS

Technology

Subject	Level	Years of experience
С	Low	2
C++	Medium	4
C#	Low	1
CI/CD	Medium	3
Camera Calibration	High	3
Computer Vision	High	12
Deep Learning	High	9
Git	High	7
Machine Learning	High	12
MLOps	Medium	4
MATLAB	High	5
Python	High	10
Pytorch	High	6
Research	High	10
ROS (Robot Operating System)	Medium	4
Sensor Fusion	Medium	3
Tensorflow / Keras	High	5

Selected Publications

Abstract

Mar. 23	Development and validation of deep learning based embryo selection across multiple days of transfer Nature, Scientific Reports J.T. Lassen, M.F. Kragh, J. Rimestad, M.N. Johansen, J. Berntsen
Feb. 22	Robust and generalizable embryo selection based on artificial intelligence and time-lapse image sequences PLoS ONE J. Berntsen, J. Rimestad, J. Lassen, D. Tran, M.F. Kragh
Oct. 21	Predicting embryo viability based on self-supervised alignment of time- lapse videos IEEE Transactions on Medical Imaging M.F. Kragh, J. Rimestad, J. Lassen, J. Berntsen, H. Karstoft
Jun. 21	Embryo selection with artificial intelligence: how to evaluate and compare methods? Journal of Assisted Reproduction and Genetics M.F. Kragh, H. Karstoft
Jun. 21 Abstract	Calibration of artificial intelligence (AI) models is necessary to reflect actual implantation probabilities with image-based embryo selection ESHRE: European Society of Human Reproduction and Embryology M.F. Kragh, J. Lassen, J. Rimestad, J. Berntsen
Sep. 20	Opening the black box: relation between Al-predicted embryo implan-

tation and traditional morphokinetic and morphological annotations

ASRM: American Society for Reproductive Medicine J. Berntsen, J. Rimestad, J. Lassen, M.F. Kragh

Jun. 20 Abstract	Robust embryo scoring model based on artificial intelligence (AI) applied to a large time-lapse dataset ESHRE: European Society of Human Reproduction and Embryology J. Rimestad, M.F. Kragh, J. Lassen, A. Tran, J. Berntsen
Oct. 19	Automatic grading of human blastocysts from time-lapse imaging Computers in Biology and Medicine M.F. Kragh, J. Rimestad, J. Berntsen, H. Karstoft
Jul. 19	UnsuperPoint: End-to-end Unsupervised Interest Point Detector and Descriptor arXiv preprint arXiv:1907.04011 P.H. Christiansen, M.F. Kragh, Y. Brodskiy, H. Karstoft
Jun. 19 Abstract	Automatic morphological grading of human blastocysts with time-lapse imaging and artificial intelligence ESHRE: European Society of Human Reproduction and Embryology M.F. Kragh, J. Rimestad, J. Berntsen, H. Karstoft
Mar. 19	Multi-Modal Obstacle Detection in Unstructured Environments with Conditional Random Fields Journal of Field Robotics M. Kragh, J. Underwood
Apr. 18 Dissertation	Lidar-Based Obstacle Detection and Recognition for Autonomous Agricultural Vehicles PhD Dissertation, AU Library Scholarly Publishing Services M.F. Kragh
Mar. 18	Multi-Modal Detection and Mapping of Static and Dynamic Obstacles in Agriculture for Process Evaluation Frontiers in Robotics and Al T. Korthals, M. Kragh, P. Christiansen, H. Karstoft, R.N. Jørgensen, U. Rück-
	ert
Nov. 17	ert FieldSAFE: Dataset for Obstacle Detection in Agriculture MDPI Sensors M. Kragh, P. Christiansen, M.S. Laursen, M. Larsen, K.A. Steen, O. Green, H. Karstoft, R.N. Jørgensen
Nov. 17 Aug. 17	FieldSAFE: Dataset for Obstacle Detection in Agriculture MDPI Sensors M. Kragh, P. Christiansen, M.S. Laursen, M. Larsen, K.A. Steen, O. Green,
	FieldSAFE: Dataset for Obstacle Detection in Agriculture MDPI Sensors M. Kragh, P. Christiansen, M.S. Laursen, M. Larsen, K.A. Steen, O. Green, H. Karstoft, R.N. Jørgensen Towards Inverse Sensor Mapping in Agriculture International Conference on Intelligent Robots and Systems, Workshop
Aug. 17	FieldSAFE: Dataset for Obstacle Detection in Agriculture MDPI Sensors M. Kragh, P. Christiansen, M.S. Laursen, M. Larsen, K.A. Steen, O. Green, H. Karstoft, R.N. Jørgensen Towards Inverse Sensor Mapping in Agriculture International Conference on Intelligent Robots and Systems, Workshop T. Korthals, M.F. Kragh, P. Christiansen, U. Rückert Platform for evaluating sensors and human detection in autonomous mowing operations Precision Agriculture

Automatic behaviour analysis system for honeybees using computer vision Computers and Electronics in Agriculture G. J. Tu, M. K. Hansen, P. Kryger, P. Ahrendt Towards a DSL for Perception-Based Safety Systems International Workshop on Domain-Specific Languages and models for Robotic systems J.T.I. Mogensen, S. Suvei, M. K. Hansen, P. Christiansen, U. P. Schultz Advanced sensor platform for human detection and protection in autonomous farming European Conference on Precision Agriculture P. Christiansen, M. Kragh, K. A. Steen, H. Karstoft, R. N. Jørgensen Jul. 15 Object Detection and Terrain Classification in Agricultural Fields using 3D Lidar Data International Conference on Computer Vision Systems M. K. Hansen, R. N. Jørgensen, H. Pedersen Feb. 12 Kinect depth sensor evaluation for computer vision applications Technical report M. Andersen, T. Jensen, P. Lisouski, A. Mortensen, M. Hansen, T. Gregersen, and P. Ahrendt	Jun. 16 Poster	Self-supervised Traversability Assessment in Field Environments with Lidar and Camera International Conference on Agricultural Engineering M. K. Hansen, J. Underwood, H. Karstoft
International Workshop on Domain-Specific Languages and models for Robotic systems J.T.I. Mogensen, S. Suvei, M. K. Hansen, P. Christiansen, U. P. Schultz Advanced sensor platform for human detection and protection in autonomous farming European Conference on Precision Agriculture P. Christiansen, M. Kragh, K. A. Steen, H. Karstoft, R. N. Jørgensen Jul. 15 Object Detection and Terrain Classification in Agricultural Fields using 3D Lidar Data International Conference on Computer Vision Systems M. K. Hansen, R. N. Jørgensen, H. Pedersen Kinect depth sensor evaluation for computer vision applications Technical report M. Andersen, T. Jensen, P. Lisouski, A. Mortensen, M. Hansen, T. Gregersen,	Jan. 16	vision Computers and Electronics in Agriculture
tonomous farming European Conference on Precision Agriculture P. Christiansen, M. Kragh, K. A. Steen, H. Karstoft, R. N. Jørgensen Object Detection and Terrain Classification in Agricultural Fields using 3D Lidar Data International Conference on Computer Vision Systems M. K. Hansen, R. N. Jørgensen, H. Pedersen Kinect depth sensor evaluation for computer vision applications Technical report M. Andersen, T. Jensen, P. Lisouski, A. Mortensen, M. Hansen, T. Gregersen,	Sep. 15	International Workshop on Domain-Specific Languages and models for Robotic systems
3D Lidar Data International Conference on Computer Vision Systems M. K. Hansen, R. N. Jørgensen, H. Pedersen Kinect depth sensor evaluation for computer vision applications Technical report M. Andersen, T. Jensen, P. Lisouski, A. Mortensen, M. Hansen, T. Gregersen,	Jul. 15	tonomous farming European Conference on Precision Agriculture
Technical report M. Andersen, T. Jensen, P. Lisouski, A. Mortensen, <u>M. Hansen</u> , T. Gregersen,	Jul. 15	3D Lidar Data International Conference on Computer Vision Systems
	Feb. 12	Technical report M. Andersen, T. Jensen, P. Lisouski, A. Mortensen, <u>M. Hansen</u> , T. Gregersen,